

Introduction to Pytorch

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Pytorch and Computational graph

- **Dynamic computation:** The graph is re-computed for each input (similarly to what we implement previous week)
- **Eager:** Each operation is immediatly computed (**no** lazy computation)

→ Since Pytorch 2 an option to compile the code is possible \implies Not eager computation

Interface

- Python (used in the exercise labs)
- C++

Pytorch components

- `torch`: Tensors (a node in the computational graph)
- `torch.nn.functional`: functions to manipulates the Tensors
- `torch.nn`: neural network components/blocks (e.g. Linear/Affine transformation and more complex blocks)
- `torch.optim`: optimization methods (e.g. SGD, Adam, RMSProp,...)

PyTorch Tensors

`torch.Tensor`

- **dtype**: the type of the tensor
- **shape**: shape/size of the tensor
- **device**: where the tensor is located (on the cpu/gpu)
- **requires_grad**: do we need to backpropagate gradient to this tensor (e.g, input rarely needs it)

Create an uninitialized tensor:

```
import torch

t = torch.empty(
    (4, 2, 2), # shape
    dtype=torch.float,
    device="cpu",
    requires_grad=True
)
```

```
tensor([[[[ 2.1968e-19,  4.5067e-41],
          [ 2.1968e-19,  4.5067e-41]],
        [[-7.6702e+08,  3.3659e-41],
          [ 0.0000e+00,  0.0000e+00]],
        [[ 0.0000e+00,  0.0000e+00],
          [-7.6806e+08,  3.3659e-41]],
        [[-9.8235e+07,  3.3659e-41],
          [ 3.0484e-23,  4.5067e-41]]],
       requires_grad=True)
```

Create an initialized tensor:

```
torch.zeros((4, 2, 2), dtype=torch.float, requires_grad=True)
torch.ones((4, 2, 2), dtype=torch.float, requires_grad=True)
torch.rand((4, 2, 2), dtype=torch.float, requires_grad=True)
```

Using `[...].like:`

Create a new tensor with the same attributes than the one given in arguments:

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- Shape are the same

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- Specific attributes can be overridden (type, value)
- Shape are the same

```
t2 = torch.zeros_like(t)
t_bool = torch.zeros_like(t, dtype=torch.bool)
t3 = torch.full_like(t2,1) # all value are one
```

Using clone:

```
t1 = torch.ones((1,))  
t2 = t1.clone()  
t2[0] = 3  
print(t1, t2)
```

Using clone:

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```

Output ?

```
tensor([1.]) tensor([3.])
```

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Output ?

```
tensor([1.]) tensor([3.])
```

Using new ?

Create a tensor of the same type as the current one (on the same device)

```
x = torch.ones((2,), device="cpu")
y = x.new()
```

Using clone:

```
t1 = torch.ones((1,))
t2 = t1.clone()
t2[0] = 3
print(t1, t2)
```

Output ?

```
tensor([1.]) tensor([3.])
```

Using new ?

Create a tensor of the same type as the current one (on the same device)

```
x = torch.ones((2,), device="cpu")
y = x.new() → tensor([])
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Using clone:

```
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Create a tensor of the same type as the current one (on the same device)

```
x = torch.ones((2,), device="cpu")  
y = x.new()
```

→ tensor([])

```
x = torch.ones((2,))  
y = x.new(3,2)
```

Using clone:

```
t1 = torch.ones((1,))
t2 = t1.clone()
t2[0] = 3
print(t1, t2)
```

Output ?

```
tensor([1.]) tensor([3.])
```

Using new ?

Create a tensor of the same type as the current one (on the same device)

```
x = torch.ones((2,), device="cpu")
y = x.new() → tensor([])
```

```
x = torch.ones((2,))
y = x.new(3,2) → tensor([[ -9.0229e+08,  3.3659e-41],
        [-7.6788e+08,  3.3659e-41],
        [-9.2275e+17,  7.0065e-45]])
```

From python list:

```
t1 = torch.tensor([0, 1, 2, 3], dtype=torch.long)
```

- Create a vector with integers 0,1,2,3
- Elements are long integers

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```
t1 = torch.tensor([0, 1, 2, 3], dtype=torch.long)
```

- Create a vector with integers 0,1,2,3
- Elements are long integers

From iterables:

```
t2 = torch.tensor(range(10))  
t3 = torch.tensor(np.array([1,2,3,4,5]))
```

- t2 is a vector of floats with values from 0 to 9
- t3 is a vector of floats with values from 1 to 5

Creating matrices:

```
t3 = torch.tensor([[0, 1], [2, 3]])
```

- First row: 0, 1
- Second row: 2, 3

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- First row: 0, 1
- Second row: 2, 3

Creating random matrices:

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
t2 = torch.randn((4, 4)) # standardized normal law
```

Copy base operations (Out-of-place)

- Create a new tensor, i.e. new memory is allocated to store the result
- Set backpropagation information if required (as in previous exercise lab)
if at least one of the inputs require grad

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Inplace operations

- Modify the data of the tensor (`x.data`)
- Contain underscore in their names
- Can lead to error computing gradient
 - Forget forward value
 - Can break the backpropagation

Introduction to PyTorch: Copy operations

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
t2 = torch.rand((4, 4)) # standardized normal law
```

Introduction to PyTorch: Copy operations

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
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```

Addition

```
t3 = torch.add(t1, t2)  
t3 = t1.add(t2)  
t3 = t1 + t2
```

Introduction to PyTorch: Copy operations

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t1 = torch.rand((4, 4)) # uniform between 0 and 1  
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t3 = torch.add(t1, t2)  
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```

Substraction

```
t3 = torch.sub(t1, t2)  
t3 = t1.sub(t2)  
t3 = t1 - t2
```

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
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Addition

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t3 = torch.add(t1, t2)  
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t3 = torch.sub(t1, t2)  
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t3 = t1 - t2
```

Multiplication (Adamad)

```
t3 = torch.mul(t1, t2)  
t3 = t1.mul(t2)  
t3 = t1 * t2
```

⚠ Not matrix multiplication

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1
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t3 = torch.sub(t1, t2)
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Multiplication (Adamad)

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t3 = torch.mul(t1, t2)
t3 = t1.mul(t2)
t3 = t1 * t2
```

⚠ Not matrix multiplication

Division

```
t3 = torch.div(t1, t2)
t3 = t1.div(t2)
t3 = t1 / t2
```

```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
t2 = torch.rand((4, 4)) # standardized normal law
```

Matrix multiplication

```
t3 = torch.matmul(t1, t2)  
t3 = t1.matmul(t2)  
t3 = t1 @ t2
```

Introduction to PyTorch: Inplace operation





```
t1 = torch.rand((4, 4)) # uniform between 0 and 1  
t2 = torch.rand((4, 4)) # standardized normal law
```

Inplace

```
t1.add_(t2)  
t1.sub_(t2)  
t1.mul_(t2)  
t1.div_(t2)
```

Introduction to PyTorch: Broadcasting

$$c = a + b$$

 =  +   Invalid dimensions

The diagram illustrates an invalid broadcasting operation. Matrix c is a 3x3 grid, matrix a is a 3x3 grid, and vector b is a 1x3 grid. The addition of a and b is shown to be invalid because their dimensions do not match for broadcasting.

Introduction to PyTorch: Broadcasting

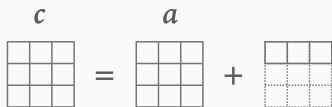
$$c = a + \begin{array}{|c|c|c|} \hline & & \\ \hline & & \\ \hline & & \\ \hline \end{array}$$

The diagram illustrates the broadcasting operation $c = a + b$. Matrix c is a 3x3 grid. Matrix a is a 3x3 grid. Matrix b is a 2x3 grid with its bottom row shown as a dotted line, indicating it is broadcasted to match the height of a .



Copy rows so that dimensions are correct

Introduction to PyTorch: Broadcasting

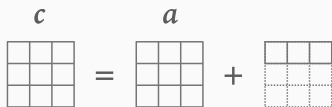


Copy rows so that
dimensions are correct

Explicit broadcasting

```
a = torch.rand((3, 3))
b = torch.rand((1, 3))
# explicitly copy the data
b.repeat((3, 1))
# implicit construction
# (no duplicated memory)
b.expand((3, -1))
```

Introduction to PyTorch: Broadcasting



Copy rows so that
dimensions are correct

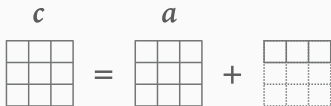
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Implicit broadcasting

Many operations will automatically
broadcast

Introduction to PyTorch: Broadcasting



Copy rows so that dimensions are correct

Explicit broadcasting

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```

Implicit broadcasting

Many operations will automatically broadcast

→ **⚠ Read the doc**

```
a = torch.rand((3, 3))
b = torch.rand((1, 3))
c = a + b
```

<https://pytorch.org/docs/stable/notes/broadcasting.html>

Einstein sum:

Sums the product of the elements of the input operands along dimensions specified using a notation based on the Einstein summation convention.

$$ij, jk \rightarrow ik$$

i , j and k correspond to dimensions of tensors

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- The right side (after \rightarrow) corresponds to the output
- Each input is separated by a comma in the inputs
- If same dimension are in the input, dim are multiplied

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- The left side (before \rightarrow) corresponds to inputs
- The right side (after \rightarrow) corresponds to the output
- Each input is separated by a comma in the inputs
- If same dimension are in the input, dim are multiplied
- If dimension are in input and not in input it is summed in the output

Examples

```
# outer product
x = torch.randn(5)
y = torch.randn(4)
torch.einsum('i,j->ij', x, y)

# batch matrix multiplication
As = torch.randn(3, 2, 5)
Bs = torch.randn(3, 5, 4)
torch.einsum('bij,bjk->bik', As,
             Bs)
```

```
# permutation of last two
  dimensions
A = torch.randn(2, 3, 4, 5)
torch.einsum('...ij->...ji', A).
  shape

# equivalent to As * Bs
As = torch.randn(3, 2, 5)
Bs = torch.randn(3, 2, 5)
torch.einsum('bij,bij->bij', As,
             Bs)
```

⚠ Use it only if you master pytorch See

<https://pytorch.org/docs/stable/generated/torch.einsum.html>

Out-of-place

```
t2 = torch.relu(t1)
t2 = torch.tanh(t1)
t2 = torch.sigmoid(t1)
```

Inplace

```
torch.relu_(t1)
torch.tanh_(t1)
torch.sigmoid_(t1)
```

Introduction to PyTorch: Backpropagation

```
a = torch.FloatTensor([2])  
b = torch.FloatTensor([4])  
c = a * b
```

→

⚠ RuntimeError: element 0 of tensors does not require grad and does not have a grad_fn

```
c.backward()
```

→ Does not register the gradient computation function

```
a = torch.FloatTensor([2])  
b = torch.FloatTensor([4])  
a.requires_grad = True  
c = a * b
```

→

a.grad get the gradient (4)

```
# after the call a.grad  
# contains the gradient
```

```
c.backward()
```

Providing a gradient to backward

We can provide an initial gradient to the backward

```
a = torch.FloatTensor([2])
b = torch.FloatTensor([4])
a.requires_grad = True
c = a * b
# after the call a.grad
#   contains the gradient
c.backward(torch.tensor([2.]))
```

→ a.grad get the gradient (8)

Double backward ?

```
a = torch.FloatTensor([2])
b = torch.FloatTensor([4])
a.requires_grad = True
c = a * b
# after the call a.grad
#   contains the gradient
c.backward()

# let's do something else...
b2 = torch.FloatTensor([2])
c2 = a * b2
c2.backward()
```

→

a.grad get the gradient (6)

⚠ The gradient is accumulated !!!

→ use `a.grad.zero_()` to set the gradient to zero !!

Let compute d :

$$tmp \leftarrow a \times b$$

$$d \leftarrow tmp \times c$$

Introduction to PyTorch: Backpropagation and inplace operation

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Introduction to PyTorch: Backpropagation and inplace operation

Let compute d :

$$tmp \leftarrow a \times b$$

$$d \leftarrow tmp \times c$$



Back-propagation to tmp

- We need the value of d
- We don't need the value of tmp

Introduction to PyTorch: Backpropagation and inplace operation

Let compute d :

$$\begin{aligned} tmp &\leftarrow a \times b \\ d &\leftarrow tmp \times c \end{aligned}$$



```
a = torch.rand((1,), requires_grad=True)
b = torch.rand((1,), requires_grad=True)
c = torch.rand((1,), requires_grad=True)
tmp = a * b
d = tmp * c
# erase the data of tmp
torch.zero_(tmp)
d.backward()
```

Back-propagation to tmp

- We need the value of d
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Introduction to PyTorch: Backpropagation and inplace operation

Let compute d :

$$\begin{aligned}tmp &\leftarrow a \times b \\ d &\leftarrow tmp \times c\end{aligned}$$



```
a = torch.rand((1,), requires_grad=True)
b = torch.rand((1,), requires_grad=True)
c = torch.rand((1,), requires_grad=True)
tmp = a * b
d = tmp * c
# erase the data of tmp
torch.zero_(tmp)
d.backward()
```

Back-propagation to tmp

- We need the value of d
- We don't need the of tmp

→

⚠ RuntimeError: one of the variables needed for gradient computation has been modified by an inplace operation

Introduction to PyTorch: Backpropagation and inplace operation

Let compute d :

$$tmp \leftarrow a \times b$$

$$d \leftarrow tmp \times c$$



```
a = torch.rand((1,)), requires_grad=True)
b = torch.rand((1,)), requires_grad=True)
c = torch.rand((1,))
tmp = a * b
d = tmp * c
# erase the data of tmp
torch.zero_(tmp)
d.backward()
```

Back-propagation to tmp

- We need the value of d
- We don't need the of tmp

→ It works !!

Introduction to PyTorch: Where are stored the gradient function ?

```
a = torch.FloatTensor([2])
b = torch.FloatTensor([4])
a.requires_grad = True
c = a * b
# after the call a.grad contains the gradient
c.backward()
```

- `d.grad_fn` is the function (`MulBackward0`)
- `d.grad_fn._saved_[]` contains saved tensors
- `d.grad_fn.next_functions` contains next function to calls

Neural Network

`torch.nn.Module`

To build a neural network, we store in a module:

- Parameters of the network
- Other modules

Benefits

- Execution mode: we can set the network in training or in test mode (e.g. to automatically apply or discard dropout)
- Move whole network to a device
- Retrieve all learnable parameters of the network (as in previous exercise lab)

Single Hidden Layer (1st version)

```
class HiddenLayer(torch.nn.Module):
    def __init__(self, input_dim, output_dim):
        super().__init__()
        self.W = torch.nn.Parameter(
            torch.empty(input_dim, output_dim)
        )
        self.bias = torch.nn.Parameter(torch.empty(output_dim, 1))
    def forward(self, x):
        z = x @ self.W.data.transpose(0, 1) \
            + self.bias.data.transpose(0, 1)
        return torch.relu(z)
```

```
nn = HiddenLayer(10, 2)
x = torch.rand((64, 10))
# Shape of y is (64, 5)
y = nn(x)
```

⚠ Do not call forward explicitly

Single Hidden Layer (2nd version)

```
class HiddenLayer(torch.nn.Module):
    def __init__(self, input_dim, output_dim):
        super().__init__()
        self.linear = torch.nn.Linear(input_dim, output_dim)

    def forward(self, inputs):
        z = self.linear(inputs)
        return torch.relu(z)
```

```
nn = HiddenLayer(10, 2)
x = torch.rand((64, 10))
# Shape of y is (64, 5)
y = nn(x)
```

⚠ Do not call forward explicitly

- Extend `torch.nn.module`
- Attributes requesting update should be `Module`

One layer neural network

```
class SimpleNetwork(torch.nn.Module):  
    def __init__(self, input_dim, hidden_dim, n_classes):  
        super().__init__()  
        self.z_proj = torch.nn.Linear(input_dim, hidden_dim)  
        self.output_proj = torch.nn.Linear(hidden_dim, n_classes)  
    def forward(self, inputs):  
        z = torch.relu(self.z_proj(inputs))  
        o = self.output_proj(z)  
        return o
```

```
class SimpleNetwork2(torch.nn.Module):  
    def __init__(self, input_dim, hidden_dim1, hidden_dim2,  
                 n_classes):  
        super().__init__()  
        self.z_projs = [] # Never do this !!!!  
        self.z_projs.append(torch.nn.Linear(input_dim, hidden_dim1))  
        self.z_projs.append(torch.nn.Linear(hidden_dim1, hidden_dim2))  
    ))
```

- **⚠ Never create a Python list of modules in a module**
- At least if you need to get the parameters (later)

```
class SimpleNetwork2(torch.nn.Module):
    def __init__(self, input_dim, hidden_dim1, hidden_dim2,
                 n_classes):
        super().__init__()
        self.z_projs = [] # Never do this !!!!
        self.z_projs.append(torch.nn.Linear(input_dim, hidden_dim1))
        self.z_projs.append(torch.nn.Linear(hidden_dim1, hidden_dim2
        ))
```

Module inspection

Pytorch will automatically inspect attributes of modules, e.g. to extract all parameters of a network. However, only appropriate containers will be recursively inspected:

- `torch.nn.Module`
- `torch.nn.ModuleList`
- `torch.nn.ParameterDict`
- `torch.nn.ParameterList`

Introduction to PyTorch: ModuleList

```
class SimpleNetwork2(torch.nn.Module):
    def __init__(self, input_dim, hidden_dim1, hidden_dim2,
                 n_classes):
        super().__init__()
        self.z_projs = torch.nn.ModuleList()
        self.z_projs.append(torch.nn.Linear(input_dim, hidden_dim1))
        self.z_projs.append(torch.nn.Linear(hidden_dim1, hidden_dim2
        ))
        self.output_proj = torch.nn.Linear(hidden_dim2, n_classes)
    def forward(self, inputs):
        z = inputs
        for nn in self.z_projs:
            z = torch.relu(nn(z))
        o = self.output_proj(z)
        return o
```

-  If you need a list of modules use ModuleList

Optimization

Introduction to PyTorch: Loss function

```
loss_builder = torch.nn.NLLLoss(reduction="mean")  
loss = loss_builder(y, gold)  
  
epoch_loss += loss.item() ## use item
```

- If you only want to show a value → use item
- Else the computation graph not entirely release (you created a new node)

Introduction to PyTorch: Parameters Update

```
nn = SimpleNetwork2(10, 250, 100, 2)
optimizer = torch.optim.SGD(
    nn.parameters(),
    lr=0.01,
    weight_decay=0.0001,
    momentum=0.9
)
# Forward
x = torch.rand((64, 10))
y = nn(x)
loss = loss_builder(y, gold)
# backward
optimizer.zero_grad()
loss.backward()
optimizer.step()
```

- Many optimizers are available out of the box

- Many optimizers are available out of the box
- More recent techniques are often available on GitHub (RAdam, ...)

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```
torch.optim.Adam(nn.parameters())  
torch.optim.Adadelta(nn.parameters())  
torch.optim.Adagrad(nn.parameters())
```

Introduction to PyTorch: Train and eval

```
class SimpleNetwork2(torch.nn.Module):
    def __init__(self, input_dim, hidden_dim1, n_classes):
        super().__init__()
        self.seq = torch.nn.Sequential(
            torch.nn.Linear(input_dim, hidden_dim1),
            torch.nn.ReLU(),
            torch.nn.Dropout(0.2), # 10% component set to 0
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Introduction to PyTorch: Train and eval

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x = torch.rand((64, 10))
nn.train()
y = nn(x)
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